Mr. Wenbin ZHOU

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EDUCATION BACKGROUND

♦	Department of Electrical and Electronic Engineering, The University of Hong Kong	Oct 2023- present
	Ph.D. Candidate in Computational Imaging & Mixed Representation Lab, advisor Yifan (Evan) Peng	
♦	Department of Computer Science, The University of Hong Kong	Sep 2022- Aug 2023
	Master of Science in Computer Science (with Distinction), GPA: 4.20/4.30	
♦	University of Science and Technology of China (USTC)	
	School of Physics	Aug 2014- Jun 2018
	Bachelor of Natural Science in Applied Physics, Major GPA: 3.82/4.30, Rank: 2 nd /52	
	School of Computer Science and Technology	Aug 2016- Jun 2018
	Minor in Computer Science	

Major Awards: 2016 **National Scholarship (3/355)**, 2015 Kwang-Hua Scholarship (9/355), The First Prize of 2015 Chinese Mathematics Competitions (Top 5%)

VISITING POSITIONS

•	Computer Graphics Department, Purdue University	Aug 2018- Jun 2020
	Research Assistant in High Performance Computer Graphics Lab, advisor Bedrich Benes	
•	Department of EECS, University of California, Berkeley	Jun 2017- Dec 2017
	Research Assistant, host Brian A. Barsky	
	Research Assistant, host Brian A. Barsky	

RESEARCH EXPERIENCES

◆ 3D-HoloNet | The University of Hong Kong | PhD Student
Advisor: Yifan (Evan) Peng, Assistant Professor at Department of EEE, HKU

- Proposed 3D-HoloNet, a non-iterative deep learning framework capable of generating high-fidelity 3D phase-only holograms in real-time (30 fps)
- Designed a learned, camera-calibrated wave propagation model to automatically compensate for hardware imperfections and eliminate the need for bulky optical filters
- Achieved superior reconstruction quality across multiple depth planes compared to traditional iterative methods (e.g., SGD, DPAC) while significantly reducing inference time

Publications: 3D-HoloNet: fast, unfiltered, 3D hologram generation with camera-calibrated network learning (**First Author**), published in Optics Letters (Vol. 50, No. 4, 2025).

- ♦ Holographic AR Head-up Display with Geometry Optical Combiner and Learned Calibration

 2025

 Advisor: Yifan (Evan) Peng, Assistant Professor at Department of EEE, HKU
- Developed a holographic AR-HUD prototype leveraging off-the-shelf freeform optical combiners (windshield) to reduce system cost and form factor
- Implemented a learned, camera-calibrated forward model to correct complex optical aberrations and geometric distortions induced by the curved combiner
- Validated the system experimentally, demonstrating precise 3D depth cues and aligned defocus effects consistent with realworld scenes

Publications: Empowering Head-up AR: Leveraging Holographic Display Engine, Geometry Optical Combiner, and Learned Calibration (**First Author**), to appear in SIGGRAPH Asia 2025 (Emerging Technologies).

- Calibration (**First Author**), to appear in SIGGRAPH Asia 2025 (Emerging Technologies).

 ◆ Multi-illumination-interfered Neural Holography with Expanded Eyebox 2025
- Collaborated on the development of "Pupil-HOGD," an optimization algorithm that accounts for higher-order diffraction and pupil constraints to improve image fidelity
- Contributed to the design of a dual-angle illumination system that successfully expanded the holographic display eyebox by 50% horizontally
- Integrated camera-in-the-loop (CITL) calibration to ensure consistent visual quality under dynamic pupil positions and mitigate aliasing artifacts

Publications: Multi-illumination-interfered Neural Holography with Expanded Eyebox (Co-Author), published in IEEE Transactions on Visualization and Computer Graphics (TVCG 2025).

Advisor: Yifan (Evan) Peng, Assistant Professor at Department of EEE, HKU

- ◆ Emotion Recognition from Real-Time Videos | Purdue University | Research Assistant Advisor: Bedrich Benes, George W. McNelly Professor of Technology, Purdue University
- Aug 2018- Jun 2020
- · Collected more than 800k facial images with emotion labels to retrain the VGG_S network via transfer learning
- · Adopt the Russel's model of core affect to classify the emotion into 4 quadrants and achieve 66% overall test accuracy
- Implemented a working application that is capable of reporting the user emotional state in real-time

Publications: Deep Learning-based Emotion Recognition from Real-Time Videos (**First Author**) and The Effects of Body Gestures and Gender on Viewer's Perception of Animated Pedagogical Agent's Emotions (**Second Author**), were included in *HCI International 2020* and published in *Multimodal and Natural Interaction, Springer International Publishing*.

- ♦ Vision Correcting Display Project | University of California, Berkeley | Research Assistant Jun 2017- Dec 2017 Advisor: Brian A. Barsky, professor at School of Electronic Engineer and Computer Science, UC Berkeley
- Accelerated two previous prefilter algorithms by 86% faster (210ms -> 30ms) and 99.6% faster (270s -> less than 1s)
- Created the Precise Forward Algorithm which reduced the rmse of simulation result from 24000 to 8000
- · Created the Average Filling Method and Middle Method which made the result brighter and clearer
- · Did the calculation in binocular situation by the binocular simulation algorithm and binocular prefilter algorithm
- ♦ Multiple-fluid Simulation Based on SPH Method | USTC | Research Assistant
 Advisor: Ligang Liu, professor at School of Mathematics, USTC

 Jun 2017- Jun 2018
- · Adopt the mixture model and the volume fraction with traditional SPH method to calculate the kinematics of mixed fluid
- Implemented the algorithm with particle system using C++ and Direct3D
- · Did the experiment of the dissolution process between two miscible fluids and two immiscible fluids
- Rendered the surface of the fluids using Houdini to make the results look more realistic
- ◆ Library Robot Project | USTC | Team Leader

 Advisor: Shengxiao GUAN, associate professor at School of Information Science and Technology, USTC

 Jun 2016- Oct 2016
- Wrote 10k lines of efficient code on STM32 for the project to make sure the robot could work under most circumstance
- · Proposed an innovative solution by using gyroscope to let the lift platform raising smoothly and quickly
- · Led a team with four members and finally made a practical robot helping people return the book in library automatically

EXTRACURRICULAR ACTIVITIES

◆ Student Union, School of Physical Science, USTC | Activity Group Leader

Sep 2014- Jun 2016

- · Held a fun running activity called "Color Run----The happiest 5k on the planet", with more than 300 student participants
- Organized four annual technical training speeches about computer science, including Java, Html, Mathematica, and MATLAB, to help physical students improve their coding skills

ADDITIONAL INFORMATION

- ◆ English Proficiency: TOEFL 102, GRE 321
- ◆ Software skills: Proficient in C/C++, Python, OpenGL, OpenCV, PyTorch, Unity 3D, Mathematica, MATLAB, Origin